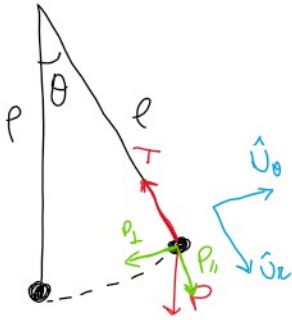


03/11/2020

martedì 3 novembre 2020 08:09

RIPASSO

MOTO DEL PENDOLO



$$\vec{F} = m\vec{a}$$

$$-\ominus \rightarrow T - mg \cos \theta = m \frac{v^2}{l}$$

$$\oplus \rightarrow -mg \sin \theta = m a_T$$

$$a_T = \frac{dv}{dt} = r \frac{d^2\theta}{dt^2} = r\alpha$$

$$v = \omega r$$

$$v = \frac{d\theta}{dt} r$$

$$-mg \sin \theta = m l \frac{d^2\theta}{dt^2}$$

$$\frac{d^2\theta}{dt^2} + \frac{g}{l} \sin \theta = 0$$

$$\frac{d^2\theta}{dt^2} + \frac{g}{l} \theta = 0 \quad \leftarrow \text{M-L}$$

identica a quella del moto armonico

$$\theta(t) = A \cos(\omega_0 t + \varphi_0)$$

NON È LA DERIVATA DI  $\theta$

$$\omega = \frac{d\theta}{dt} = -A \omega_0 \sin(\omega_0 t + \varphi_0)$$

$$\alpha = \frac{d^2\theta}{dt^2} = -A \omega_0^2 \cos(\omega_0 t + \varphi_0)$$

$$-A \omega_0^2 \cos(\omega_0 t + \varphi_0) + \frac{g}{l} A \cos(\omega_0 t + \varphi_0) = 0$$

se  $\theta(t) = A \cos(\omega_0 t + \varphi_0)$  è soluzione  
 $\Rightarrow$  req. è soddisfatta  $\forall t$

$$A \cos(\omega_0 t + \varphi_0) \left[ -\omega_0^2 + \frac{g}{l} \right] = 0 \Rightarrow \boxed{\omega_0^2 = \frac{g}{l}}$$

$$\frac{d^2\theta}{dt^2} + \frac{g}{l} \theta = 0$$

$$\omega_0 = \sqrt{\frac{g}{l}}$$

$$T = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{l}{g}}$$

$$\frac{d\theta}{dt} = -A \omega_0 \sin(\omega_0 t + \varphi_0)$$

A e  $\varphi_0$  sono costanti e si scelgono in base alle condizioni iniziali

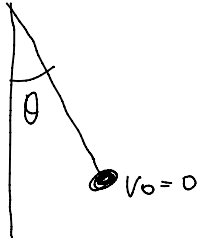
- $\theta(0) = \theta_0$
- $v(0) = 0 \rightarrow \omega \frac{d\theta}{dt}(0) = 0$

- in base alle condizioni iniziali
- $\theta(0) = \theta_0$
  - $v(0) = 0 \rightarrow \omega \frac{d\theta}{dt}(0) = 0$

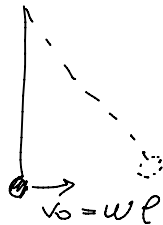
$$\begin{cases} \theta(0) = A \cos \varphi_0 = \theta_0 \\ \frac{d\theta}{dt}(0) = \omega(0) = -A \omega_0 \sin \varphi_0 = 0 \end{cases} \rightarrow \begin{cases} A = \theta_0 \\ \varphi_0 = 0 \end{cases}$$

Fissate le costanti le sostituisco nella soluzione

$$\theta(t) = \theta_0 \cos(\omega_0 t)$$



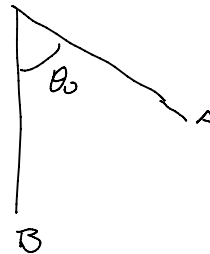
$$\theta = \theta_0 \cos(\omega t)$$



$$\theta = \theta_0 \sin(\omega t)$$

es

$$\begin{aligned} l &= 1 \text{ m} \\ m &= 2 \text{ kg} \\ \theta_0 &= \frac{\pi}{6} \quad \omega_0 = \sqrt{\frac{g}{l}} = 3,13 \text{ rad/s} \end{aligned}$$



$v_B = ?$

- ① legge oraria
- ② conservazione dell'energia

$$\begin{aligned} \text{① } v &= \omega l = \frac{d\theta}{dt} l & \theta &= \frac{\pi}{6} \cos(\omega_0 t) \\ & & \frac{d\theta}{dt} &= -\frac{\pi}{6} \omega_0 \sin(\omega_0 t) \end{aligned}$$

nel punto più basso  $\omega = -\frac{\pi}{6} \omega_0$

$$\omega_0 = \frac{2\pi}{T} \quad t = \frac{T}{4} \quad \omega_0 t = \frac{2\pi}{T} \cdot \frac{T}{4} = \frac{\pi}{2}$$

$$v_B = \frac{\pi}{6} \omega_0 l \approx 1,64 \text{ m/s}$$

↳ approssimato perché  $\sin \theta \approx \theta$

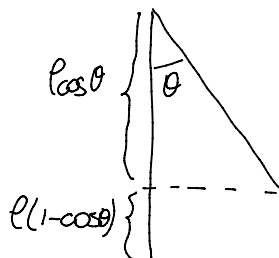
②

$$E_{TOT A} = E_{TOT B}$$

$$mgl(1 - \cos \theta) = \frac{1}{2} m v_B^2$$

$$v_B = \sqrt{2gl \left(1 - \frac{\sqrt{3}}{2}\right)} = 1,62 \text{ m/s}$$

↳ esatto



T in funzione di  $\theta$

$$T - mg \cos \theta = m \frac{v^2(\theta)}{l}$$

$$mgl(1 - \cos \theta_0) = mgl(1 - \cos \theta) + \frac{1}{2} m v^2$$

$$v^2 = 2gl(\cos \theta - \cos \theta_0)$$

$$T = mg \cos \theta + m 2g(\cos \theta - \cos \theta_0)$$

$$v = 2gl(\cos\theta - \cos\theta_0)$$

$$T = mg\cos\theta + m2g(\cos\theta - \cos\theta_0)$$

$$T(\theta) = mg(3\cos\theta - 2\cos\theta_0)$$

$$T_B(\theta) = mg(3 - 2\cos\theta_0)$$

$\theta_{max} = ?$

$$\frac{1}{2}mv_B^2 = mgl(1 - \cos\theta_{max})$$

$$\cos\theta_{max} = \frac{v_B^2}{2gl} + 1$$

$$\theta_{max} = \cos^{-1}\left(1 - \frac{v_B^2}{2gl}\right)$$

$$\omega_0 = \frac{2T}{l} = \sqrt{\frac{g}{l}} \neq \omega = \frac{d\theta}{dt}$$